

(精度)

TPM /

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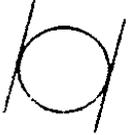
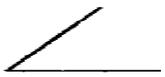
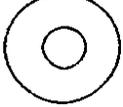
가 0.005mm

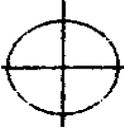
0.005mm

가

3.9.4

(1)

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			mm, <i>m</i>
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			mm, \mathbf{m}

(2)

1.	0.003mm l	*KS B 5206 1 *KS B 5207
2.	$\begin{matrix} \text{G} \\ \text{H} \end{matrix} 001 + \frac{L}{200,000} \begin{matrix} \text{H} \\ \text{K} \end{matrix} \text{mm}$	L: (mm)
	=0004mm	
	=0004mm	
3.	$\begin{matrix} \text{G} \\ \text{H} \end{matrix} 001 + \frac{L}{500,000} \begin{matrix} \text{H} \\ \text{K} \end{matrix} \text{mm}$	*L: (mm) * :
4.	: 6mm	* 가 가
5.	: ±0.002mm	
6.	KS B 5201 B	
7.	$\pm \begin{matrix} \text{G} \\ \text{H} \end{matrix} 002 + \frac{L}{200,000} \begin{matrix} \text{H} \\ \text{K} \end{matrix} \text{mm}$	L mm
8.	KS R 1352 1 , 2 KS R 5252 l , 2	

(3)
(가)
B 4001-77)

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(KSB 4001-77)

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(a)2 A, B

2 A, B

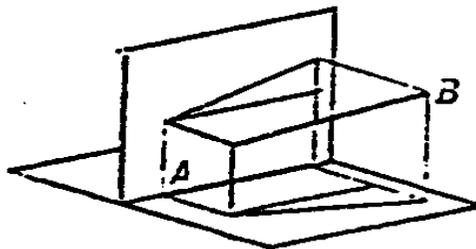
A

2 A, B

A

2

B



(b)

(c)

2

() (KSB 4001-77)

() (KSB 4001-77)

(a)2 A, B

A

B

(b)

2가

(i)

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(c)

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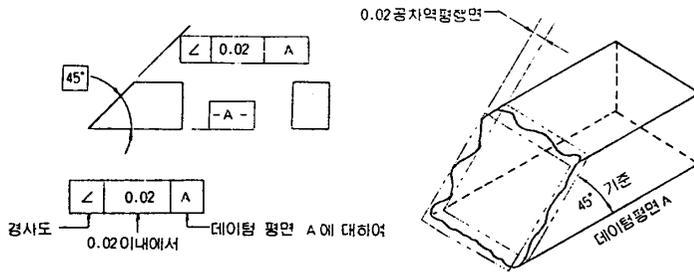
(KSB 4001-77)

()

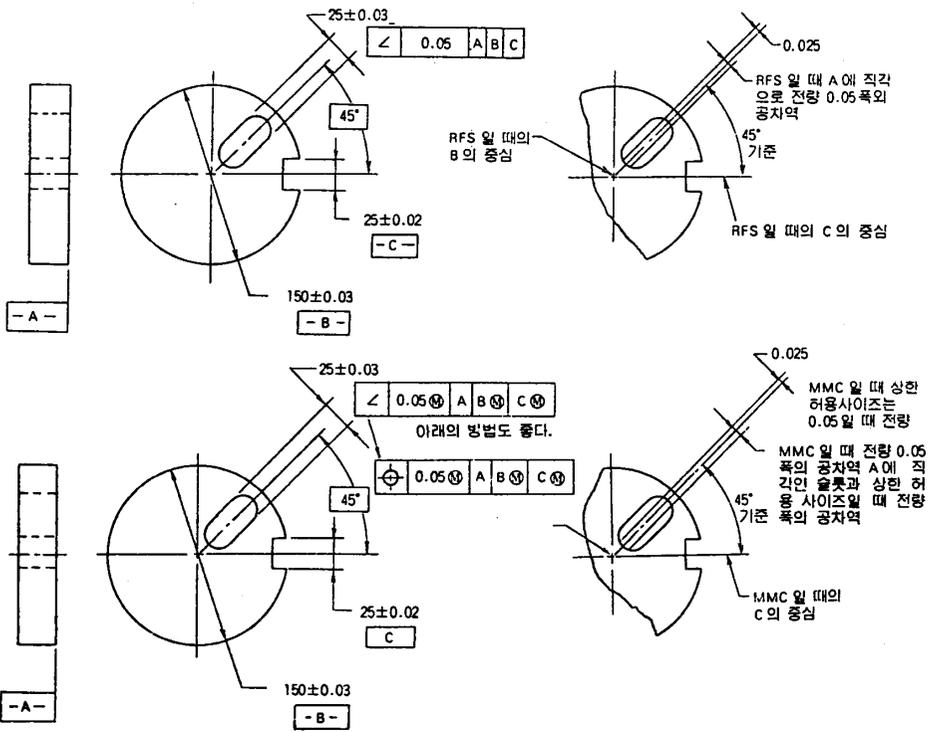
(\angle)

90 °

가



경사도 공차역



경사도규제에

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MMC

RFS

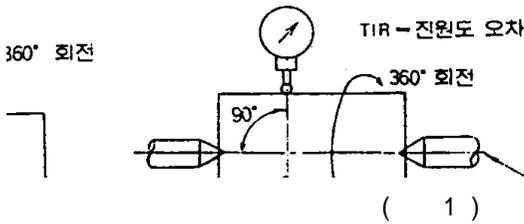


진원도 공차역

측정은 V-블록에 의한 측정법과 양 센테로 측정법
진원도 측정기에 의한 방법이 있으며, 그 예는 다
다.

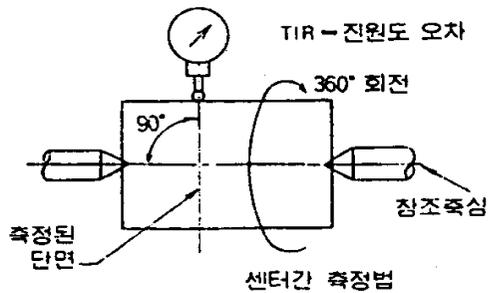
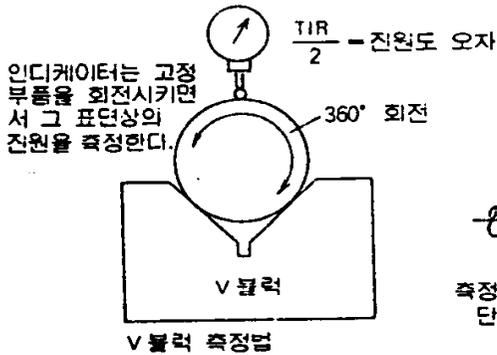
① 진원도 측정 :

--진원도 오차



인디케이터는 고정
부품을 회전시키면
서 그 표면상의
진원을 측정한다.

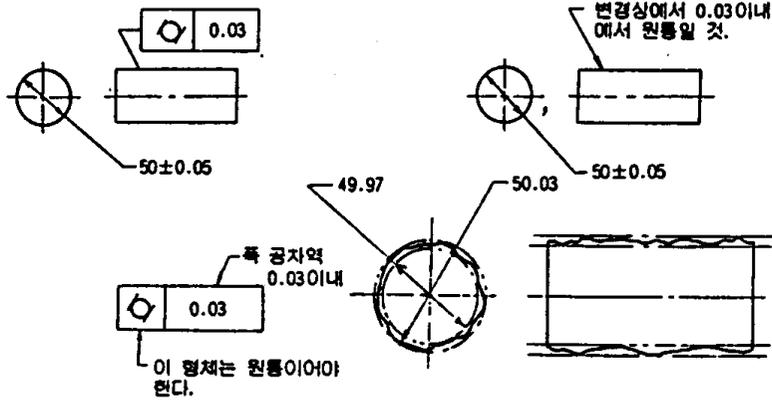
V-



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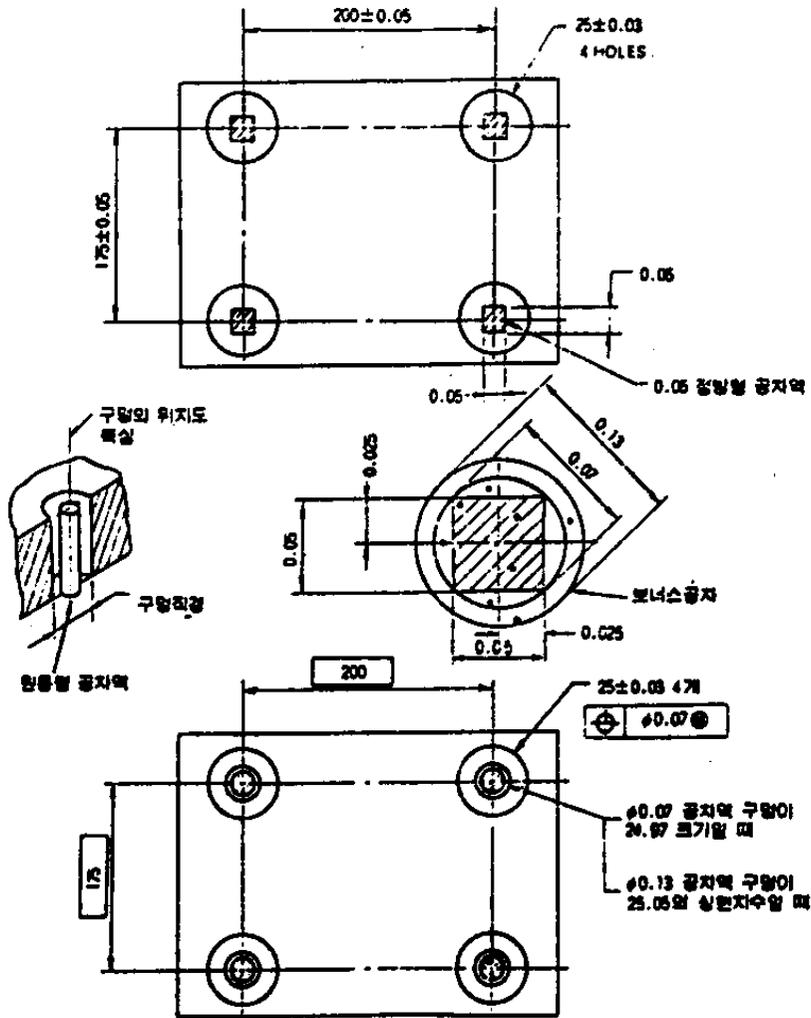
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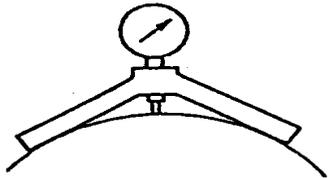


위치도 공차방식과 직교좌표 방식의 비교

(4)가 (KSB 4001-77) 가 ,
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(a)45 ° 4 , .
(b)60 120 ° 3.9.1
(3.9.1) .



공작물
(3.9.1)

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(a) , .

(b)가 .
(c)

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(a) (b) , 2

(c) (d) .

(a)

(b)

(c)

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(a) (b) , 2

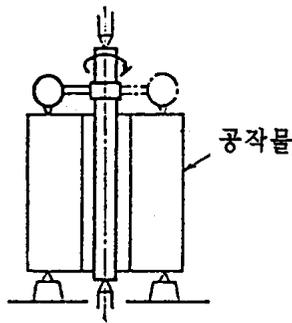
(c) (d) .

(a)

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(3.9.2) .

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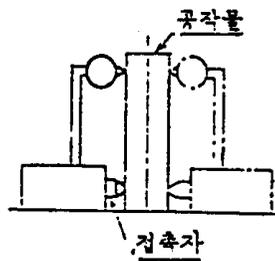
(3.9.2)

(b)

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(3.9.3)

(C)

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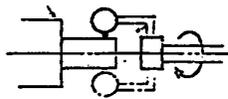
가

(a)

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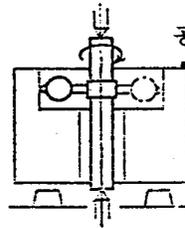
(3.9.4 (a) (b))

공작물



(a)

공작물



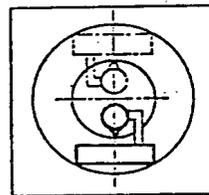
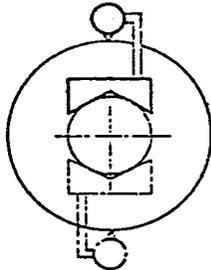
(b)

(3.9.4 (a) (b))

(b)

1/2

(3.9.5(a) (b))

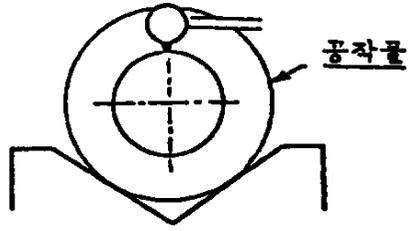


(3.9.5)

(c)

1/2

(3.9.6)



(3.9.6)

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(a) :

(b) : 2 ,

(a) :

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No	Point No					No	Point No			

3.9.5

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