

(TBM)

가 .

<

1> (Preventive Maintenance : PM) (Breakdown Maintenance : BM)

2가 .

(PM)

(Time Based Preventive Maintenance : TBM),

M TBF , , .

(Inspection & Repair : IR), (CDT)

(machine condition)

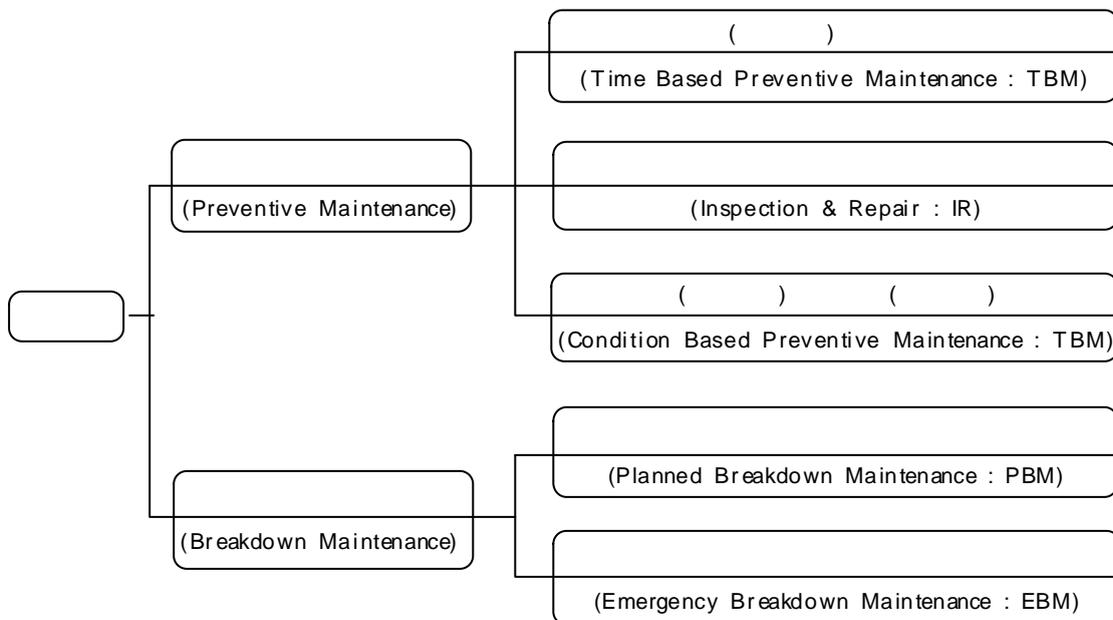
(TBM) (Condition Based Preventive Maintenance : CBM) (JIPM, 1992).

(BM)

(Planned Breakdown Maintenance : PBM)

2. (Emergency Breakdown Maintenance : EBM)

2.1 T B M (豊田, 1996). (PBM)

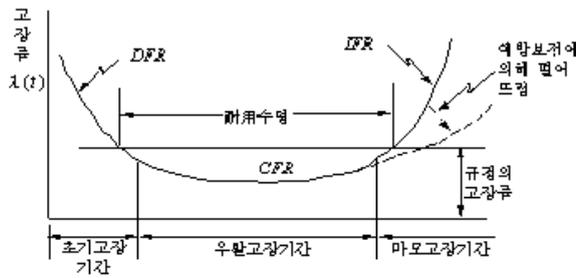


가 Overhaul
 Overhaul (TBM)
 MTBF TBO(Time
 Between Overhaul)
 (, 1998).

3. (TBM)

3.1 (TBM)

(TBM)
 $I(t)$ 가 가 IFR(Increas-
 ing Failure Rate)
 < 3> Bathtub
 (TBM)
 (L)
 (TBM)
 (豊田, 1996).



3. (Bathtub)

(川崎, 1992).

(TBM)
 : 가

$$I(t)$$

$$I(t) < 3 >$$

가 IFR

(豊田, 1996).

$I(t)$
 $I(t)$ 가 가 11%
 $I(t)$ 가 89%
 $I(t)$ 가

“TBM

.” (豊田, 1996, 川崎, 1992).

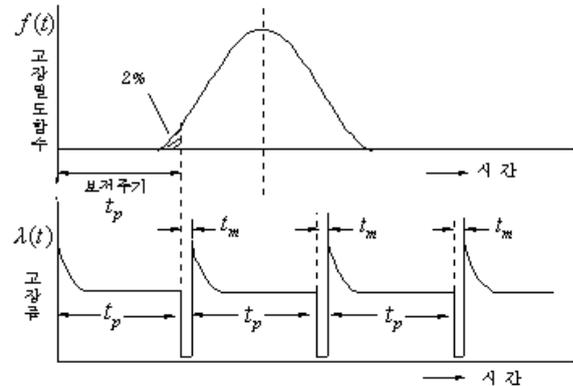
$$< 4 > \text{TBM } I(t) \text{ } f(t)$$

(TBM) , 2%가

(豊田, 1996).

2%

(가)



4. (TBM)

t_p

가 가
 $I(t)$ 가 . , 98%

t_p :
 μ : (MTBF)
 σ :

가 , TBM (σ)

가 , (1)

$I(t)$ t_p 가
 μ (TBM)

σ 3 가 TBM

(, 1998).

< 5> $f(t)$ 가

$N(m\sigma^2)$, $N(m\sigma^2) = N(5,1)$

($m=5$) 3σ (

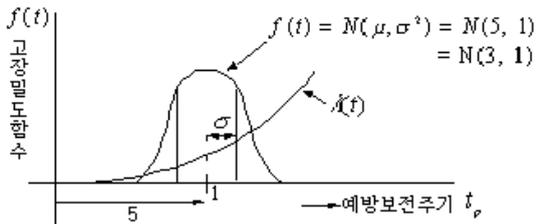
$\sigma=1$) $t=2$

$I(t)=0$

t_p 가

가

가

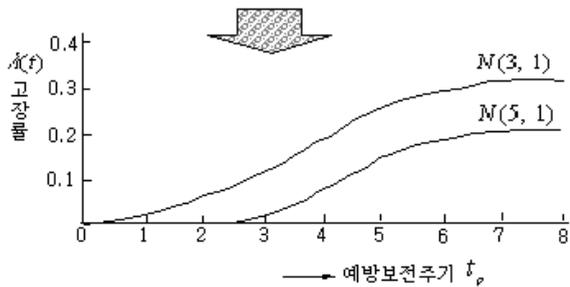


10%

()

가

가 (Availability)



(CBM)

(Predictive Maintenance)

(, 1998).

(TBM)

5. (TBM) t_p

$I(t)$

(TBM)

가

$I(t)$ 0

t_p

(豊田, 1996).

$t_p \leq m-3\sigma$

(1)

TBM

3.2

가

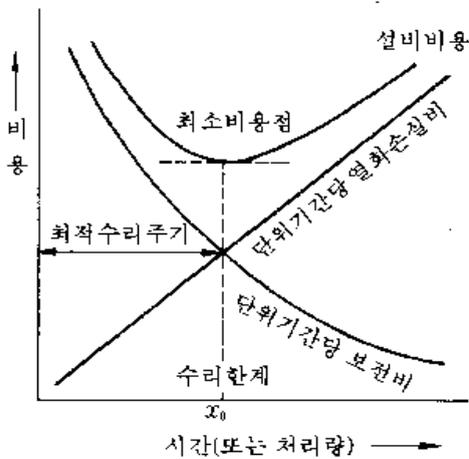
, 1993).

가

)

가

< 6> (a)



6.

$$f(x), 1 \quad a \quad (\quad) \quad ,$$

$$(\quad) \quad x_0 \quad .$$

$$= \frac{a}{x} \quad (2)$$

$$= \frac{1}{x} \int f(x) dx \quad (3)$$

$$= \frac{a}{x} + \frac{1}{x} \int f(x) dx \quad (4)$$

$$-\frac{a}{x^2} - \frac{1}{x^2} \int_0^x f(x) dx + \frac{1}{x} f(x) = 0$$

$$-a - \int_0^x f(x) dx + xf(x) = 0$$

$$xf(x) - \int_0^x f(x) dx = a \quad (5)$$

< 6> (a)

a x_0 가

() .

$$x_0 f(x_0) - \int_0^{x_0} f(x) dx = a$$

가 가 ,

< 6> (b)

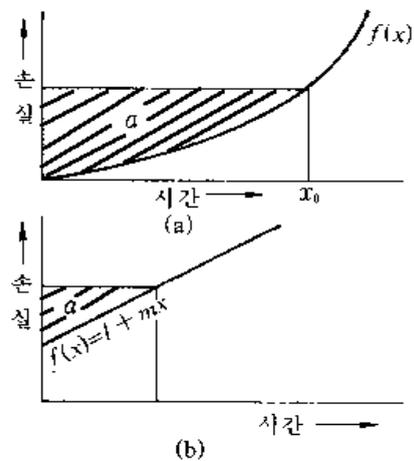
$$f(x) = l + mx \quad (6)$$

x_0

$$\int_0^{x_0} f(x) dx = \int_0^{x_0} f(l + mx) dx$$

$$= \left[lx + \frac{1}{2} mx^2 \right]_0^{x_0}$$

$$= lx_0 + \frac{1}{2} mx_0^2$$



$$x_0 f(x_0) - \int_0^{x_0} f(x) dx = a$$

$$x_0(l + mx_0) - \left(lx_0 + \frac{1}{2} mx_0^2 \right) = a$$

$$x_0 = \sqrt{\frac{2a}{m}}$$

(7)

, a=100 / , m=50 /

, x₀=2

1. K

	0.5	1	1.5	2	2.5
()	0	500	1,000	1,500	2,000
	3	3.5	4	4.5	5
x ₀ ()	3,000	4,000	5,000	7,000	10,000

10%

1

10,000,000 (9,000,000

+1,000,000)

< 2>

7>

가

()

()

(,1993)

K

< 1>

가

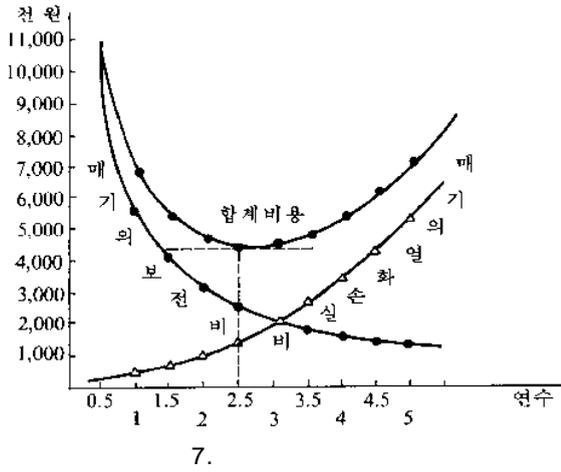
() 2,000

가

< 2>

2. 가

	(x)	가	가 (x)	가 (Σ)	(x)	/ x	(+)		
0.5	0	0	0.909	0	0	1,100	0	11,000	11,000
1	500	1,000	0.826	826	826	0.576	475	5,760	6,235
1.5	1,000	2,000	0.751	1,502	2,328	0.402	935	4,020	4,955
2	1,500	3,000	0.683	2,049	4,377	0.315	1,375	3,150	4,525
2.5	2,000	4,000	0.621	2,730	6,861	0.264	1,810	2,640	4,450
3	3,000	6,000	0.565	3,390	10,251	0.230	2,360	2,300	4,660
3.5	4,000	8,000	0.513	4,104	14,355	0.205	2,930	2,050	4,980
4	5,000	10,000	0.447	4,670	19,025	0.187	3,550	1,870	5,420
4.5	7,000	14,000	0.424	5,950	24,975	0.174	4,340	1,740	6,080
5	10,000	20,000	0.385	7,700	32,675	0.163	5,320	1,630	6,950



, T : ()
 C_i : 1
 I : ($I = 1/MTBF$)
 C_e : ()

MTBF
 가
 MTBF
 . MTBF

가
 가
 () 가
 가

. < 3> KM Ro-
 bot MTBF

4> KM Robot

3. Robot
 MTBF

('00.1 '00.12)

3.3

가 가

(, 1993).

$$T = \sqrt{\frac{2C_i}{IC_e}}$$

(8)

	가 ()	(r)	MTBF ()	I (1/MTBF)
S/Motor	4,023	5	805	1.24×10^{-3}
	4,023	16	251	3.98×10^{-3}
Nipple	4,023	5	805	1.24×10^{-3}
Bolt	4,023	11	366	2.73×10^{-3}
Arm	4,023	4	1,006	9.94×10^{-4}
Shank	4,023	4	1,006	9.94×10^{-4}
Bracket	4,023	7	575	1.74×10^{-3}
Guide	4,023	7	575	1.74×10^{-3}
	4,023	11	366	2.73×10^{-3}
	4,023	38	106	9.43×10^{-3}
Bus-Bar	4,023	44	91	1.10×10^{-2}
Trans	4,023	20	201	4.98×10^{-3}
	4,023	13	309	3.24×10^{-3}
SCR Timer	4,023	19	212	4.72×10^{-3}
Cable	4,023	43	94	1.06×10^{-2}

4. Robot Line C_e, C_i

	C_e ()	C_i ()
Robot	98,743	213,000(Gun)
		356,700()
		162,000()

C_i, C_e 가
 $< 5>, < 6>$

5. C_e : Down Time

Line			(/Hr)		(C_e)
U/B	B	3	5,400	16,200	98,743
B/S	A	10	5,400	54,000	
S/C	A	35	5,400	189,000	
PO38	A	20	5,400	108,000	
SUB	C	30	5,400	162,000	
S/F	B	20	5,400	108,000	
B/D	C	10	5,400	54,000	
		128	5,400	691,200	

6. C_i : 1 Cost

					C_i
Gun	150	6,300 /Hr	4	150,000	213,000
Robot	180	6,300 /Hr	3	300,000	356,700
	60	6,300 /Hr	2	150,000	162,600
	$C_i = (\quad \times \quad \times \quad) +$				

() -
 MTBF
 () . < 7>
 Robot ()
 ()

7. : Robot KI A

	I (1/MTBF)	C_e ()	C_i ()	T ()
S/Motor	1.24×10^{-3}	98,743	356,700	76.3
	3.98×10^{-3}	98,743	356,700	42.6
Nipple	1.24×10^{-3}	98,743	213,000	58.9
Bolt	2.73×10^{-3}	98,743	213,000	39.7
Arm	9.94×10^{-4}	98,743	213,000	65.9
Shank	9.94×10^{-4}	98,743	213,000	65.9
Bracket	1.74×10^{-3}	98,743	213,000	49.8
Guide	1.74×10^{-3}	98,743	213,000	49.8
	2.73×10^{-3}	98,743	162,000	34.7
	9.43×10^{-3}	98,743	162,000	18.6
Bus-Bar	1.10×10^{-2}	98,743	213,000	19.8
Trans	4.98×10^{-3}	98,743	356,000	38.1
	3.24×10^{-3}	98,743	356,000	49.2
SCR Timer	4.72×10^{-3}	98,743	162,000	26.4
Cable	1.06×10^{-2}	98,743	162,000	17.6

MTBF 가 ,
 가 .
 가

4.
 < 8>

3가

가

3가

3가

8.

A	10	10	10	10
B	8	8	8	8
C	5	5	5	5
	0	0	0	0
D	-5	-5	-5	-5
E	-8	-8	-8	-8
F	-10	-10	-10	-10

(Optimizing Maintenance Interval)

3가

가

가

4가

가

3가

(adjusting)

< 8 >

(Leveling)

Step 1 - (, , ,)

List-up

Step 2 : 가 . “ =가

+ ” 가

Step 3 : MTBF

(, ,) ,

MTTF

Step 4 : (, , ,)

, , 3가

, , 3가

가 가

가

“MTBF=

가 / ”,

가

“MTTF=

가 / ”

0.8

가

MTBF(or MTTF)×0.8

$$t_p \leq m - 3s$$

S

$$3S \leq 0.2m$$

가

Step 5 : Step 4

“(+ +)/n”

. 3가

n=3

Step 6 :

4가

Step 7 : $\frac{1}{20} \left(\frac{1.5}{n} + \frac{1.5}{n} \right) \times (1 + \frac{1.5}{20})$ 가 Step 5

가 10~+10

20 가 Step 8 :

+10

+10 20

9. ()

		Sifter(A)					
(Unit)		Motor					
		V	V	B/R	B/R		
(A)	# 1	4	2	6	5	1	
	()						
	# 5	2	1	5	4	4	
		2.8	1.6	5.6	5	2.4	
(B)	# 6	2	1	4	3	2	
	()						
	# 12	3	2	6	5	6	
		3..4	1.4	4.8	3.2	2.8	
(C)	# 13	2	1	3	1	1	
	()						
	# 18	4	0	3	2	4	
		2.4	0	3	2	4	
가 (HR)		72,000	72,000	72,000	72,000	72,000	
() ()		50	23	83	54	34	
MTTF, MTBF	가 / ()	1,440	3,130	867	1,333	2,117	
(HR) (A)	MTTF(or MTBF) x 0.8	1,152	2,504	693	1,066	1,693	
(HR) (B)		35,000	35,000	7,000	35,000	35,000	
(HR) (C)		21,600	35,000	4,800	28,800	35,000	
Factor		5	8	-5	8	8	
		-8	8	0	-5	-8	
		5	5	5	5	5	
		5	5	5	0	-5	
	= /4	2	5	1	2	0	
(HR) (E)	[A+B+C]/n x [1+ /20]	21,175	30,210	4,372	23,784	23,897	

CJ

MTTF()

가

MTTF × 0.8 (A) (B), (C)

A, B, C 가 (가)

< 9> 가

5. TBM IR(Inspection & Repair), (CDT)

TBM (CBM)

(JIPM, 1992).

가

가

(,)

(田口, 1998).

80%

가 ,

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